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| **Python Level 1 with Virtual Robotics**  **Mission 9 Objective 5 Line Sensor Readings** | | **Name:** | |
| Use this document to chart the line sensor readings while driving on the black line.   * Open the console and then run the code. * Stop the program execution after a few seconds. * Record the sensor readings. * Change the readings from Boolean to Binary. * Highlight each unique reading and cross out repeat readings. * Compare your chart to the one in the instructions. | | | |
| **First time it appears** | **Boolean Values** | | **Binary Values** |
| X | (False, True, True, False, False) | | (0, 1, 1, 0, 0) |
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